

Logistics Committee Mission Statement

Consistent with and in the furtherance of the bylaws and policies of NDIA, the mission of Logistics Committee of the Robotics Division will be to foster mutual understanding and effective working relationships between government and industry for the purpose of promoting the utilization of innovative, efficient and effective robot logistics support principles for national and international robotics markets.

Through a series of programs including conferences, seminars, demonstrations, and reports this committee will:

- act to promote the effective exchange of views between government and industry on matters of common concern
- provide mutual understanding and valuable working relationships to insure the design, development and execution of efficient and reliable logistics support to robots
- Provide government with the best of industry advice on government policies, practices, needs and problems that will enable government to achieve its readiness objectives for robots at reasonable cost

Committee Organization

Co-Leads:

- Tim Everhard, Foster-Miller, Inc., teverhard@foster-miller.com, 781-281-8305 (W), 617-281-8305 (C)
- Dan Sulka, iRobot Corporation, dsulka@irobot.com, 781-345-0200 (W)

Initial Ideas for Committee Membership

- Industry:
 - iRobot
 - Foster-Miller
 - John Deere
 - Boeing: FCS Director of Logistics
 - BAE: Unmanned FCS system (MGV & ARV)
 - Lockheed Martin: FCS
 - GDRS
 - NCDR rep
- Government:
 - RSJPO Director of Logistics
 - NAVEODTECH DIV Director of Logistics
 - AMC
 - TRADOC/CASCOM rep

Upcoming Activities/ Milestones

- Complete the establishment of the committee and develop tasks focused on the mission statement.
- Develop a charter
- Define initial areas of interest:
 - Sense and Respond Logistics
 - Embedded Test and Evaluation Capabilities
 - Gov't Logistics Information Management Systems
 - ERPs
 - UID/RFID
 - ITAR and export controls
 - Performance Based Logistics
 - Advanced Concepts for Robotics Training
 - Connectivity to the Field