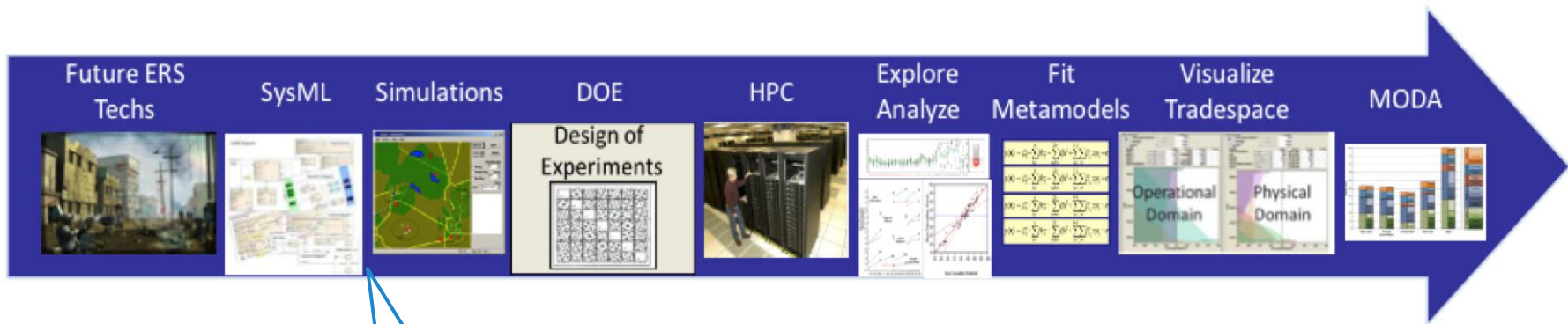


# Cloud-Based Deployment and Distributed Execution of Models

Rob Kewley, USMA



# Motivation

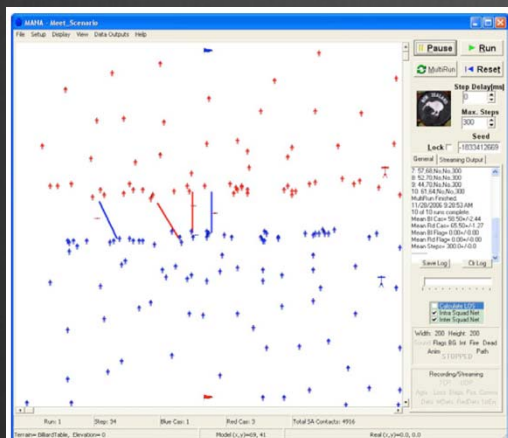


Magic  
Happens  
Here

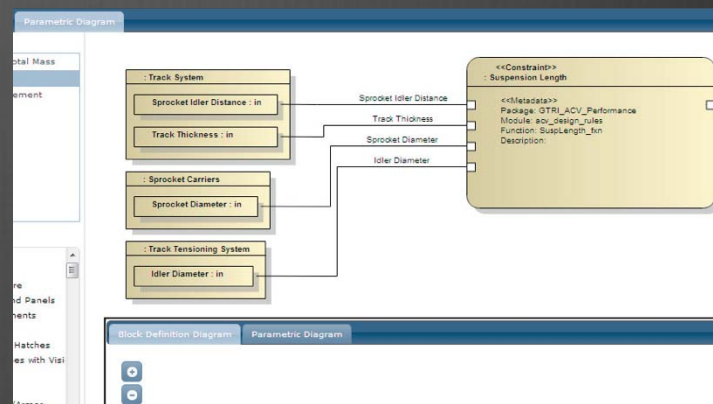
- ⊗ Chain of tools for using M&S to develop system of systems architecture
- ⊗ How to we connect the system design properties to the simulation inputs?

# Connect Systems Architecture to Executable Model

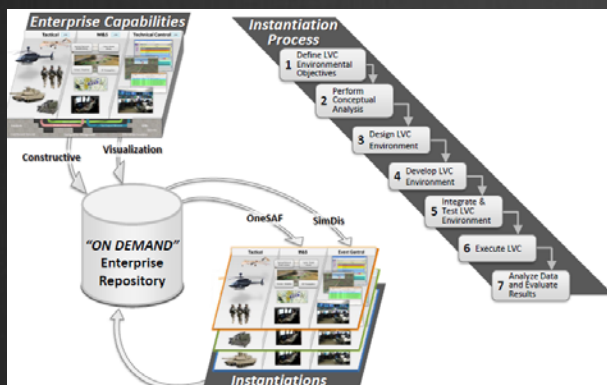
## Current Approaches



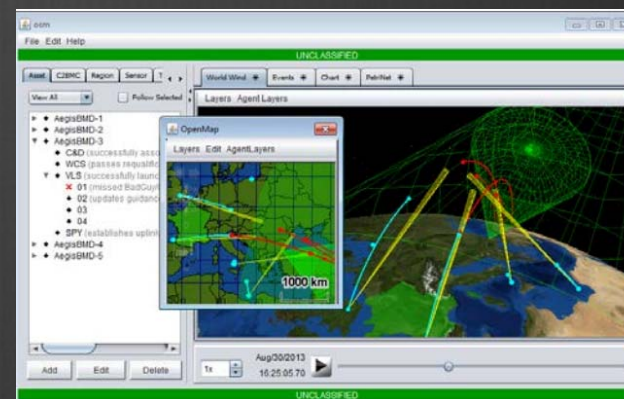
**Agent Based Models**  
*Engineering Resilient Systems*



**Link many independent models**  
*Framework for Assessing Cost and Technology*



**HLA/DIS**  
*Always On*



**Frameworks**  
*Orchestrated Simulation through Modeling*

# We have tried HLA/DIS before...



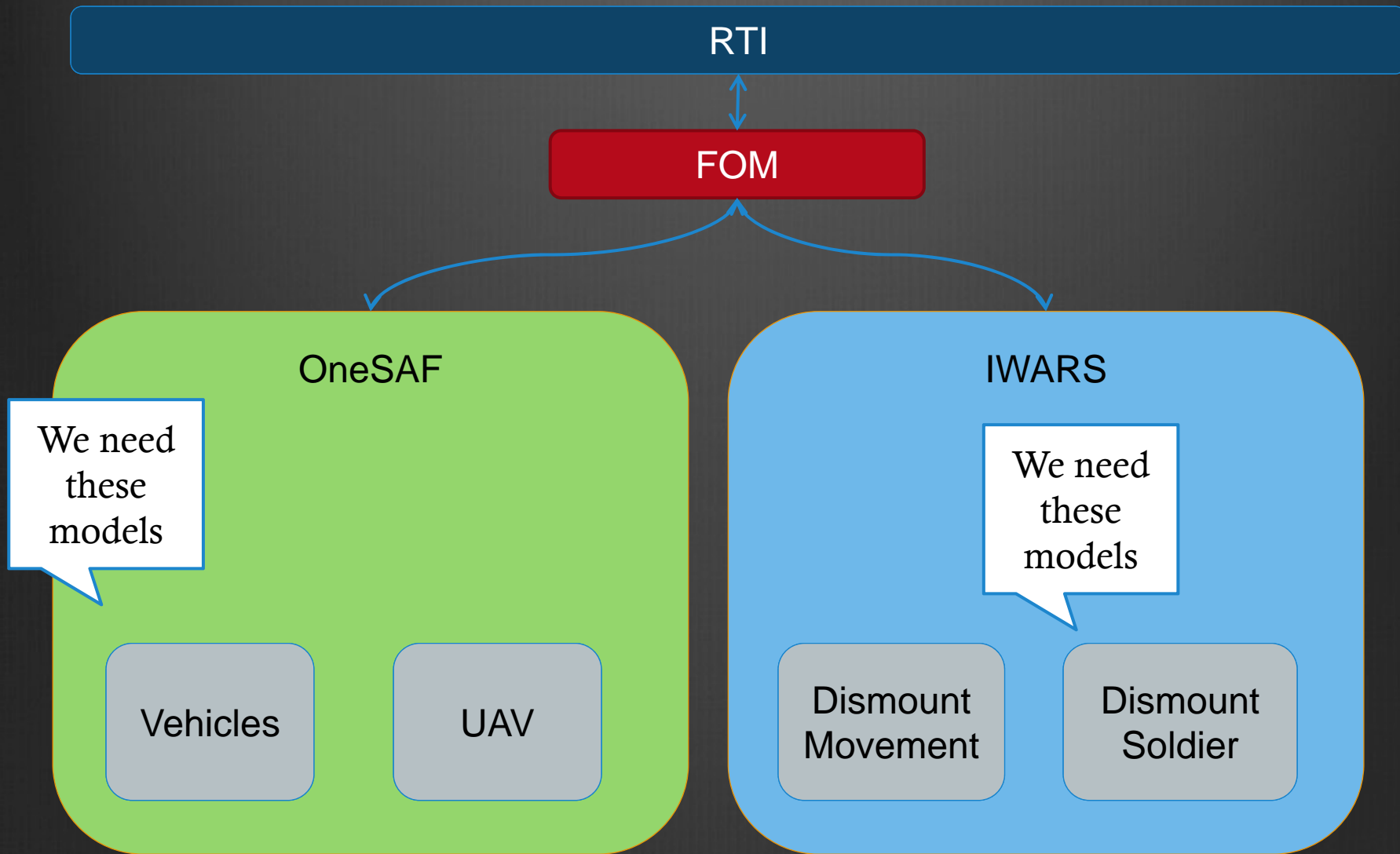
# ...HLA/DIS integration does not scale....



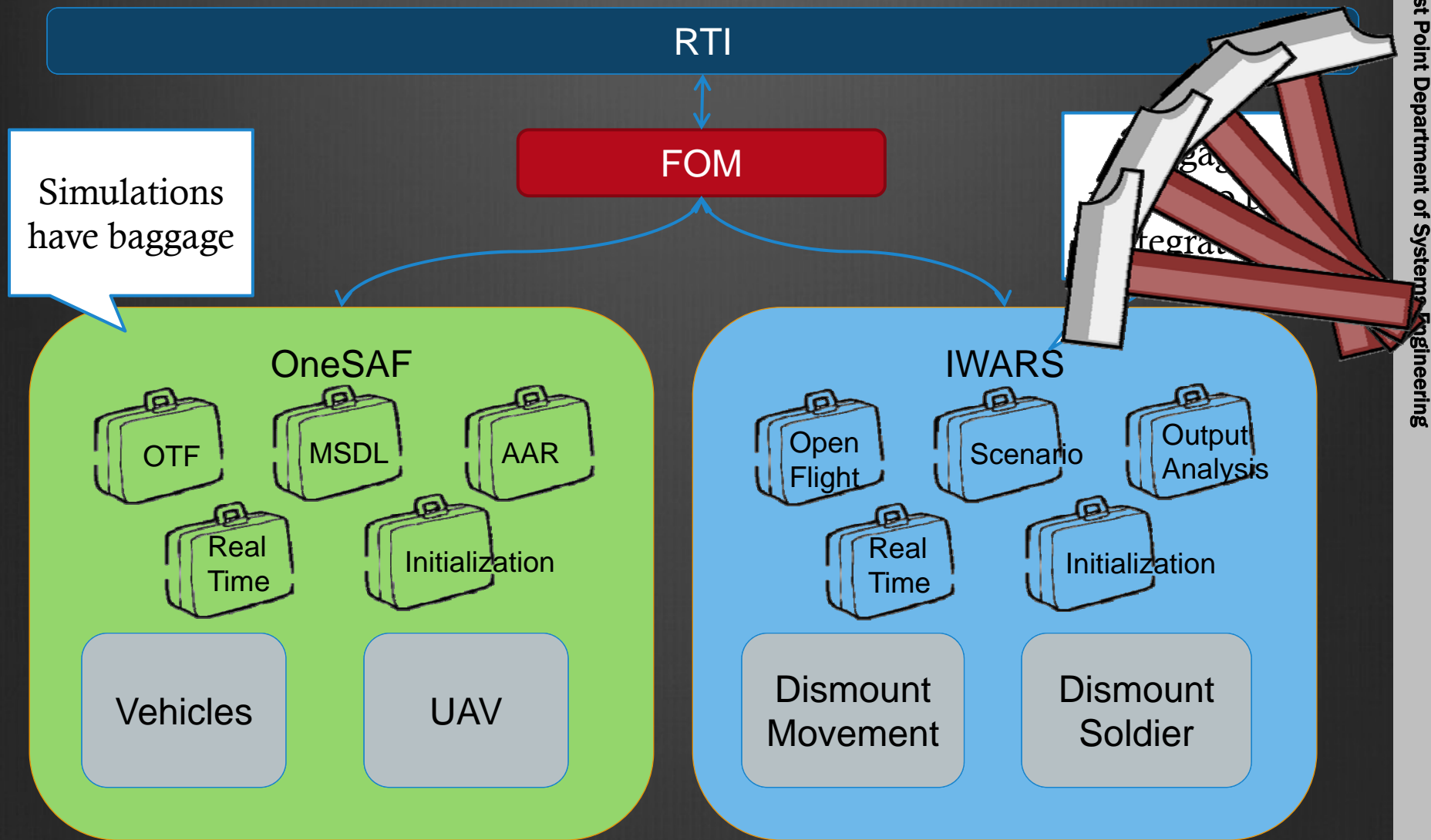
- ⦿ 5 different information exchange protocols
- ⦿ 4 different terrain databases
- ⦿ Runs only in real time
- ⦿ Complex scenario initialization must be manually coordinated across federates
- ⦿ Scenario execution is manual and error-prone
- ⦿ Data collection complex and causality can be impossible
- ⦿ Changing the scenario is a months-long proposition



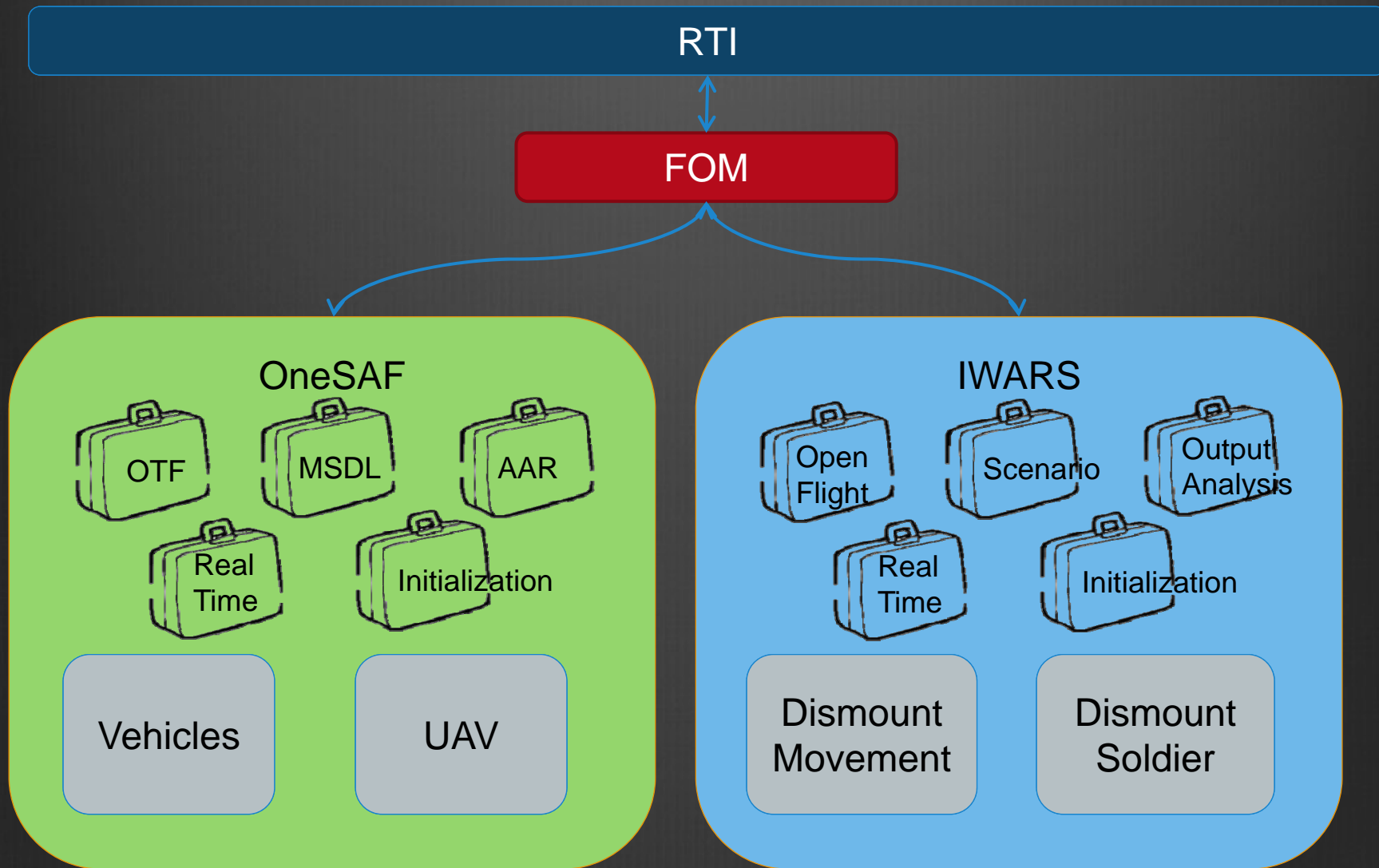
# HLA Approach



# HLA Approach



# HLA Approach





# Distributed Modeling Framework



Bring your models a “pure” state transition functions. Leave the baggage at home.

# Things to Discuss



- ⊗ Federate models, not simulations
  - ⊗ Summer vacation at AMSAA
- ⊗ Loosely managed distributed architecture
  - ⊗ Models are services via an interface (BOM)
  - ⊗ Communicate via messaging (Actor Model)
  - ⊗ Compose models in an interface (...like ProModel)
  - ⊗ Systems model (SysML) drives model parameters
  - ⊗ Distributed and parallel execution engine (DEVS-Akka)
  - ⊗ Support with design and analysis of experiments
- ⊗ Take advantage of latest advances
  - ⊗ Enterprise technologies
  - ⊗ Discrete Event Systems Specification (DEVS) models
  - ⊗ Actor model of computation
- ⊗ Proof of principle implementation
- ⊗ Target implementation for small UAS



# Web Based Modeling and Simulation for Analysis

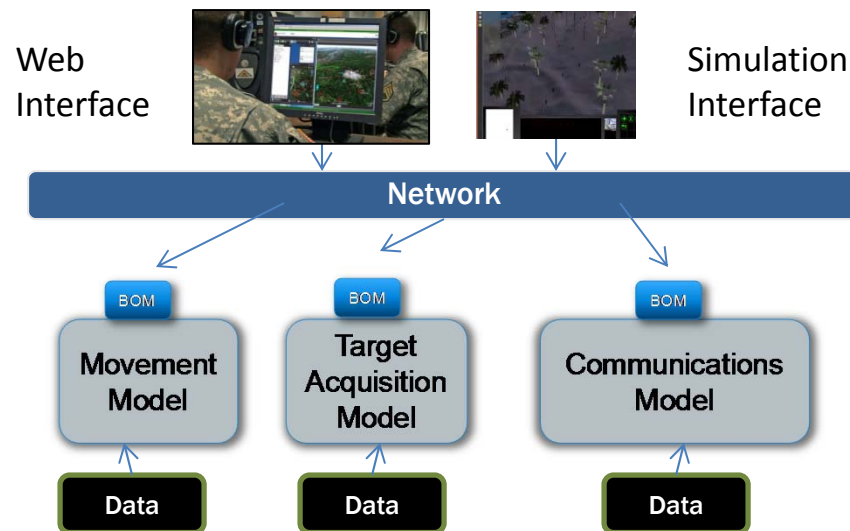
Develop capability to deploy Army models and simulations to distributed users via web a cloud technologies.



**US ARMY  
RDECOM**

**ARL**

## Technical Approach



Models as services – connected to data

## Objectives

Current Business Model	Proposed Business Model
Deploy as software	Deploy as web services
Accessed locally by a few users	Run distributed by many users
Data deployed separately	Data integrated and updated
Single programming language	Cross-platform integration of models in different languages

## Deliverables

- AMSAA models deployed on classified network as services with web and simulation interfaces
  - ACQUIRE-TTPM-TAS
  - Direct Fire Accuracy
  - Dismounted Vulnerability
  - Dismounted Mobility
  - Hand Grenade Accuracy
- Proof of principle web-based simulation integrating these models

# Acquire Service

## Acquire Service

Home Configuration

### Current Configuration

Aggregate	Attribute	Setting
Time	timeOfDay	DAY
Time	season	SUMMER
Time	hourOfDay	1300
Scene	clutter	MEDIUM
Scene	background	VEGETATION
Scene	lightLevel	1
Scene	region	URBAN
Weather	weatherCondition	15
Weather	massExtinctionCoefficient	0
Weather	attenuationCoefficient	0.326
Weather	obscurantConcentrationLength	0
Weather	tPath	0
Weather	meteorologicalVisibilityRange	12

### Service Control



Current Configuration

Turn Debugging On/Off

Play/Pause Service

Start/Stop Service

## Messages

Clear

# Acquire Test Client

## Acquire Test Client

### Message

History ▾ Example Save

Observer

**Name**  
  
Required

**Type**  

GUNNER

  
Required

**TFOV uRand1**  

Generate ⚙

  
Real

**TFOV uRand2**  

Generate ⚙

  
Real

Sensor

Target

Draw

Send

### Response

Response

**Observer:** M1A2\_DVO  
**Target:** RED1  
**Acquisition Level:** DETECTION  
**Correct ID:** false  
**TEFOV:** 3.7668386438011496

Statistics

Request sent at: May 27, 2015 at 1:52:10 PM EDT

Response received at: May 27, 2015 at 1:52:10 PM EDT

**Elapsed Time:** 0.015s

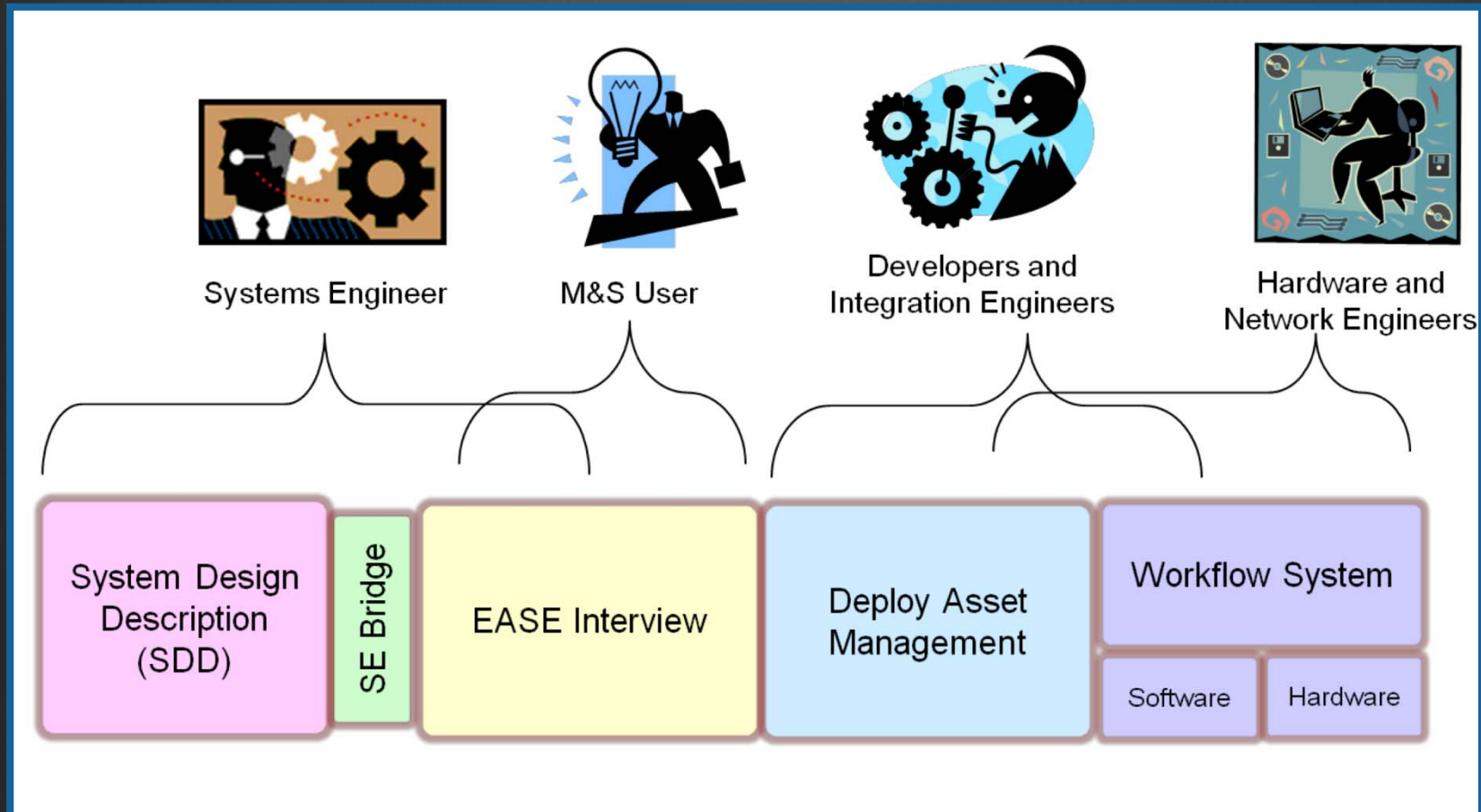
### Log Messages

Connection to server: Open  
Client Registered As: be77ad76-c3af-4684-ba43-59a374b0ed09  
Akka Websocket: Actor[akka://application/system/websockets/612/handler#-1869837053]  
Akka Remote: Actor[akka://AcquireClient/user/acquire#-2114968281]  
Connection to server: Closed  
Reason: The connection was closed abnormally, e.g., without sending or receiving a Close control frame

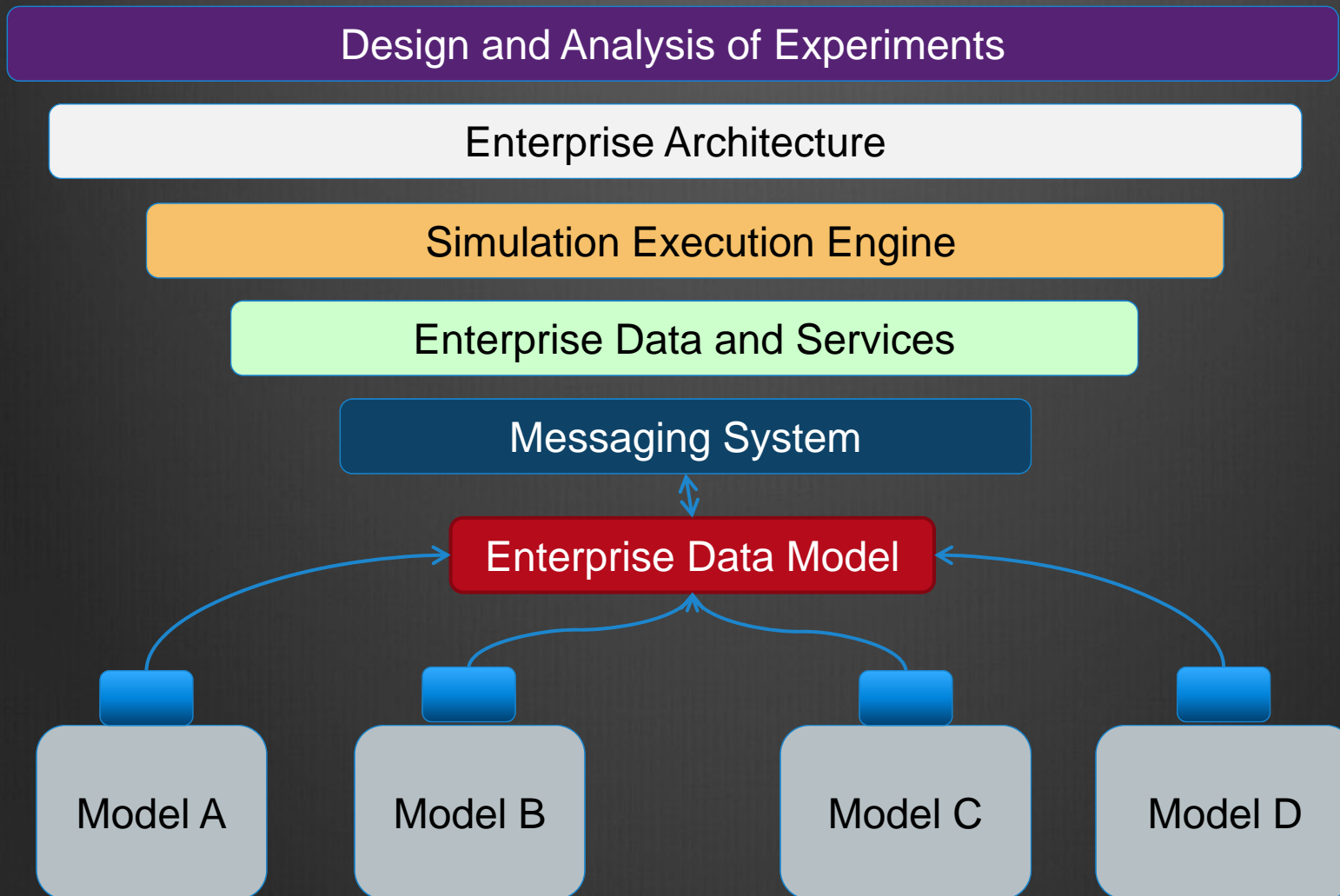


# EASE Program

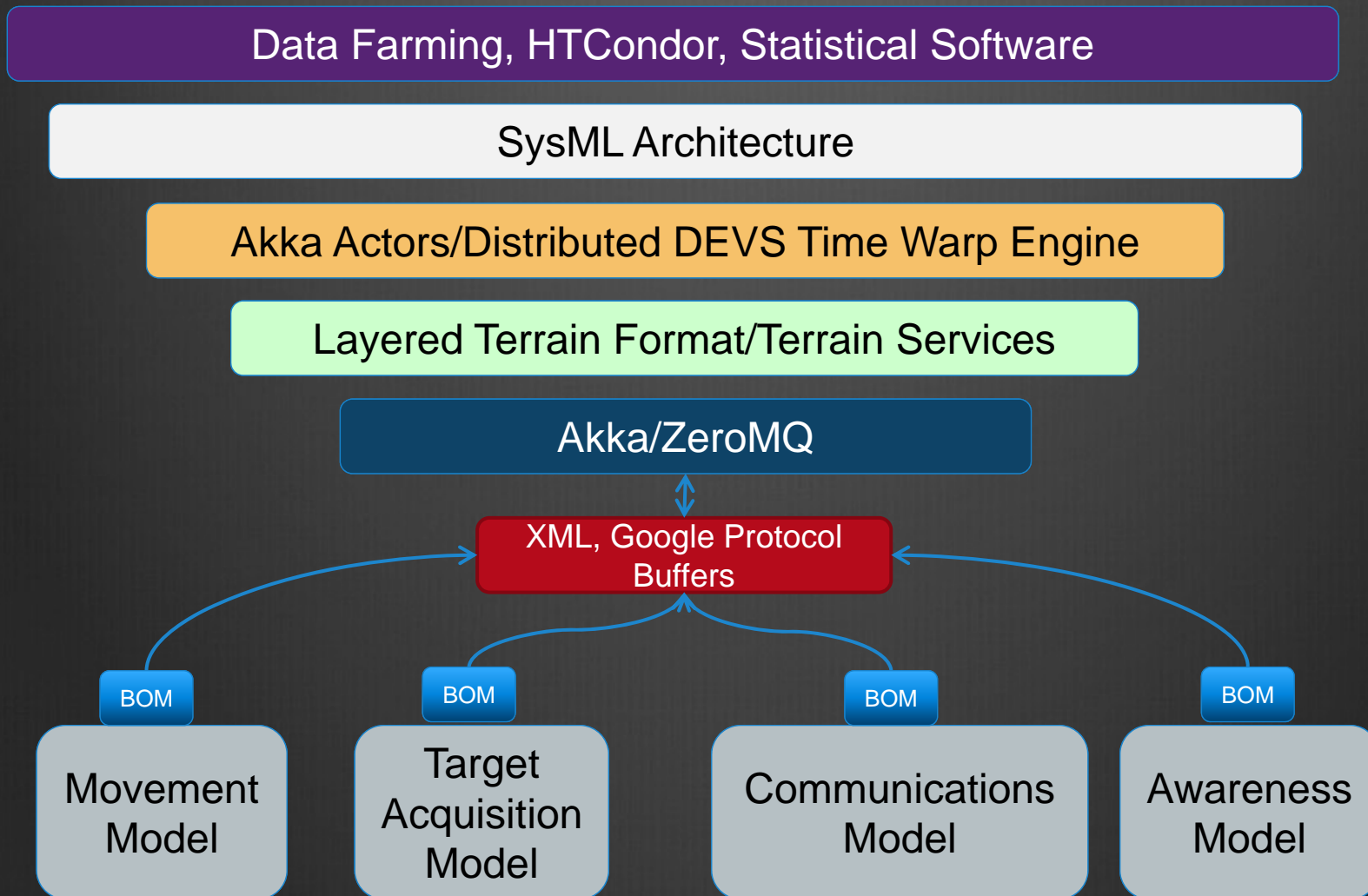
## ARL Simulation and Training Technology Center



# Enterprise Model Integration



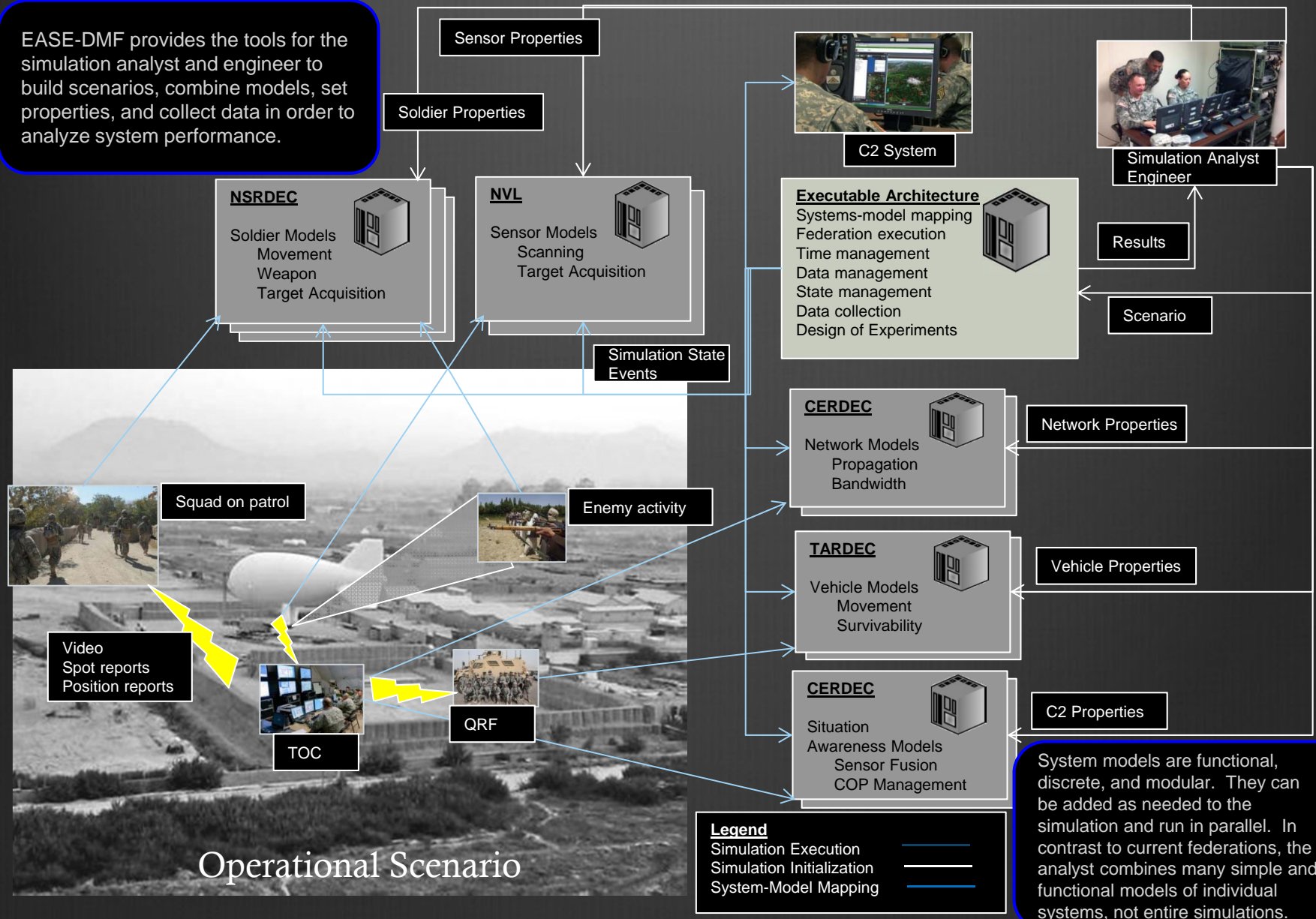
# Technology Stack



# Executable Architecture for Systems Engineering Distributed Modeling Framework (EASE-DMF)



EASE-DMF provides the tools for the simulation analyst and engineer to build scenarios, combine models, set properties, and collect data in order to analyze system performance.



# Useful Theories - Simulation



- ⦿ Discrete Event Specification (DEVS)
  - ⦿ DEVS models are modular
  - ⦿ Composable hierarchies in coupled models
  - ⦿ Strong track record
- ⦿ Base Object Model (BOM)
  - ⦿ Adds semantics to the models
  - ⦿ Complete specification of data inputs and outputs
  - ⦿ Situates models in a chain or interactions
- ⦿ Parallel algorithms
  - ⦿ Optimistic time advance – Time Warp
  - ⦿ Supports distributed and cloud-based implementations



# Useful Theories – Computer Science



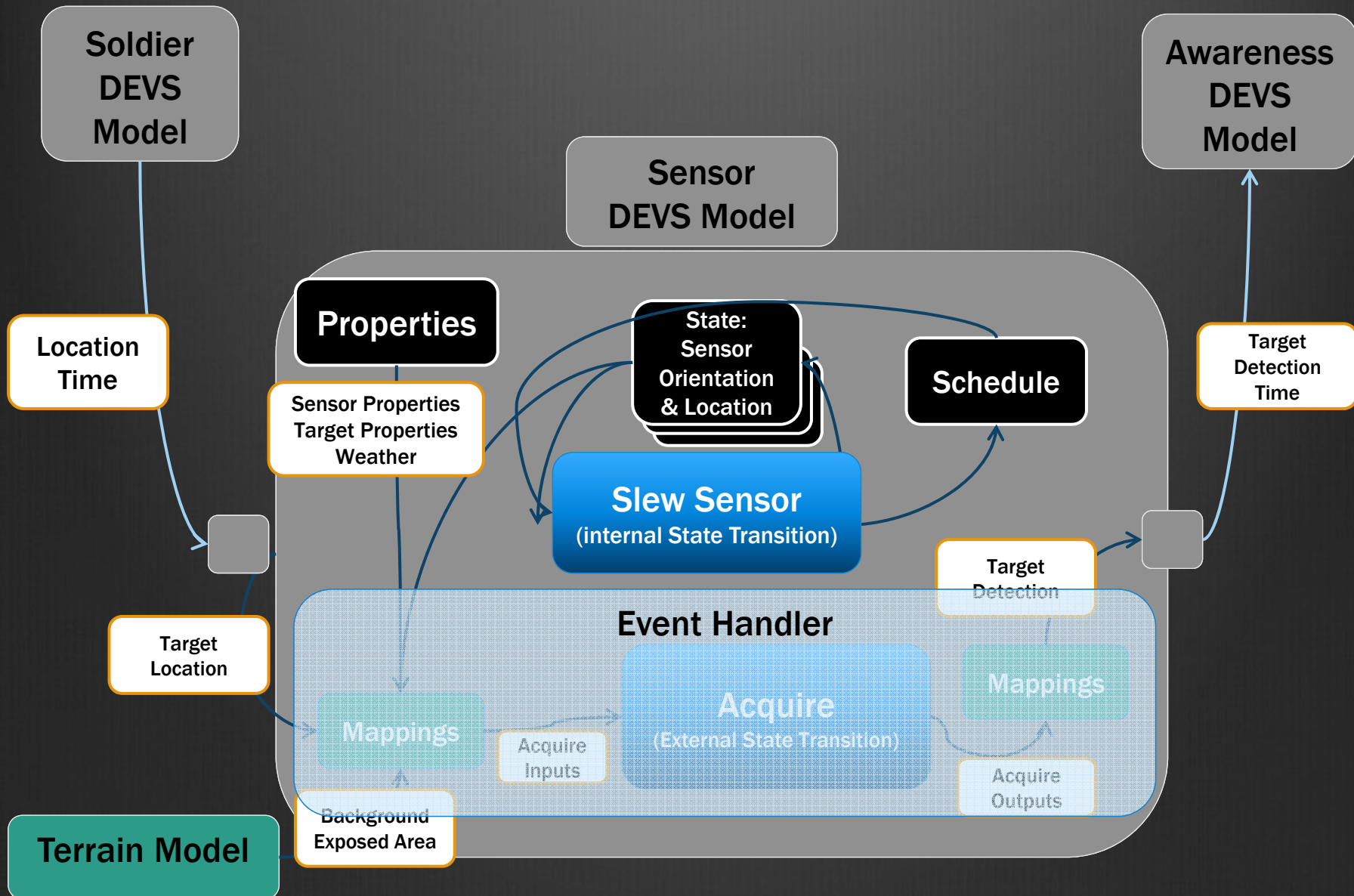
- ⊗ Functional programming
  - ⊗ Functions are composable
  - ⊗ Functions have no side effects
  - ⊗ Predictable behavior
- ⊗ Actor model of computation
  - ⊗ Encapsulation of state
  - ⊗ Responds to messages by...
    - ⊗ Sending messages to other actors
    - ⊗ Changing state in a way that influences future messages
    - ⊗ Creating new actors
  - ⊗ Reactive programming
    - ⊗ Event driven
    - ⊗ Responsive
    - ⊗ Asynchronous
    - ⊗ Loosely coupled messaging
    - ⊗ Fault tolerant

- ⦿ Implementation of reactive actor model
- ⦿ Scala and Java versions
- ⦿ Each DEVS model is an Akka SimActor
- ⦿ Each actor runs on its own thread
- ⦿ Exchanges data only through messaging
- ⦿ Support for serialization and distributed actors
- ⦿ Ability to manage threads
- ⦿ Open source



<http://akka.io>

# ACQURIE Sensor Model

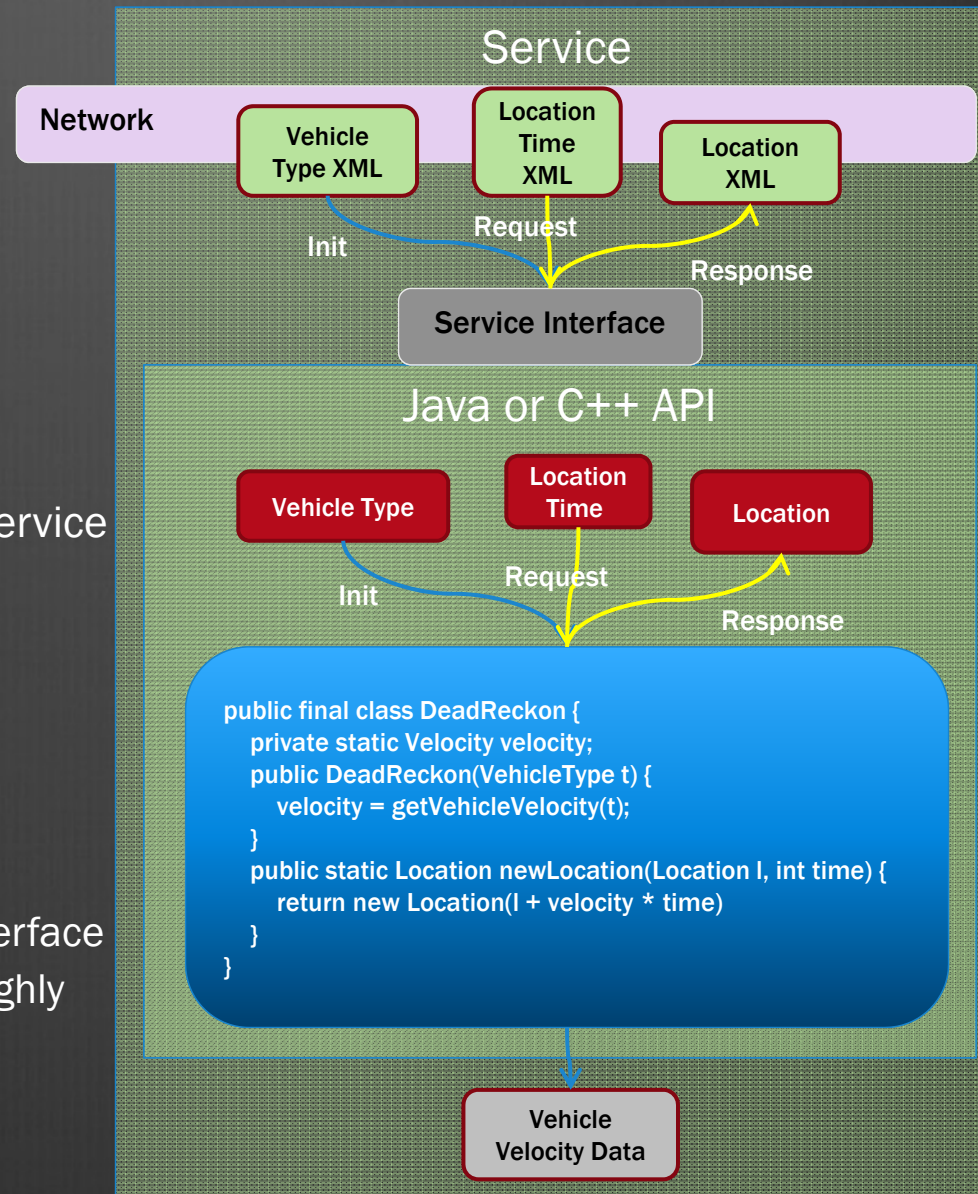




# Exposing Function Interfaces



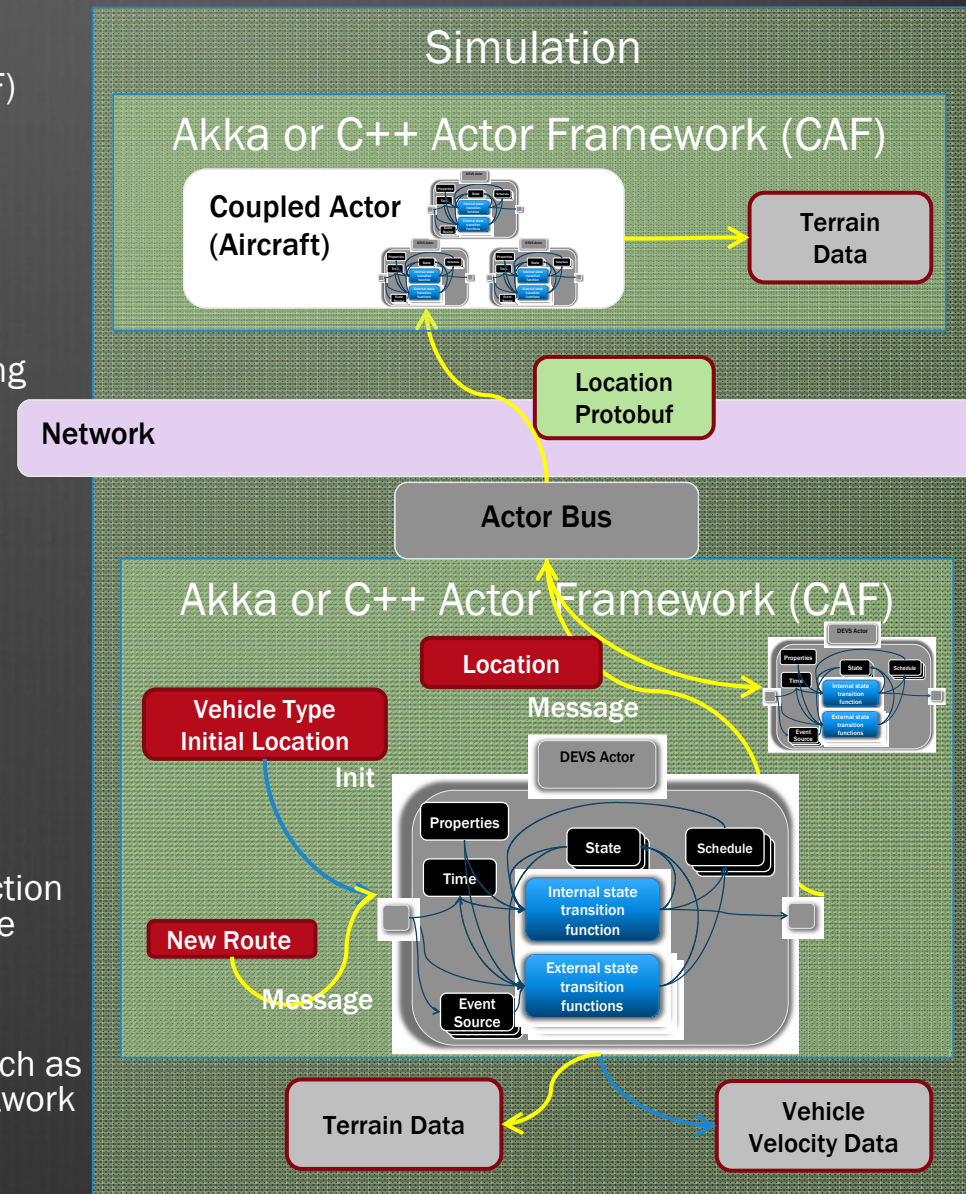
- As a class in API
  - Use static class
  - Pass in initialization data at instantiation
  - Use public static methods
- As a state transition function service
  - Define message classes for input/output
  - Map message classes to messaging protocol such as:
    - JSON
    - Protocol Buffers
    - XML
  - Expose through a service interface
  - Document everything thoroughly



# Composing DEVSActors

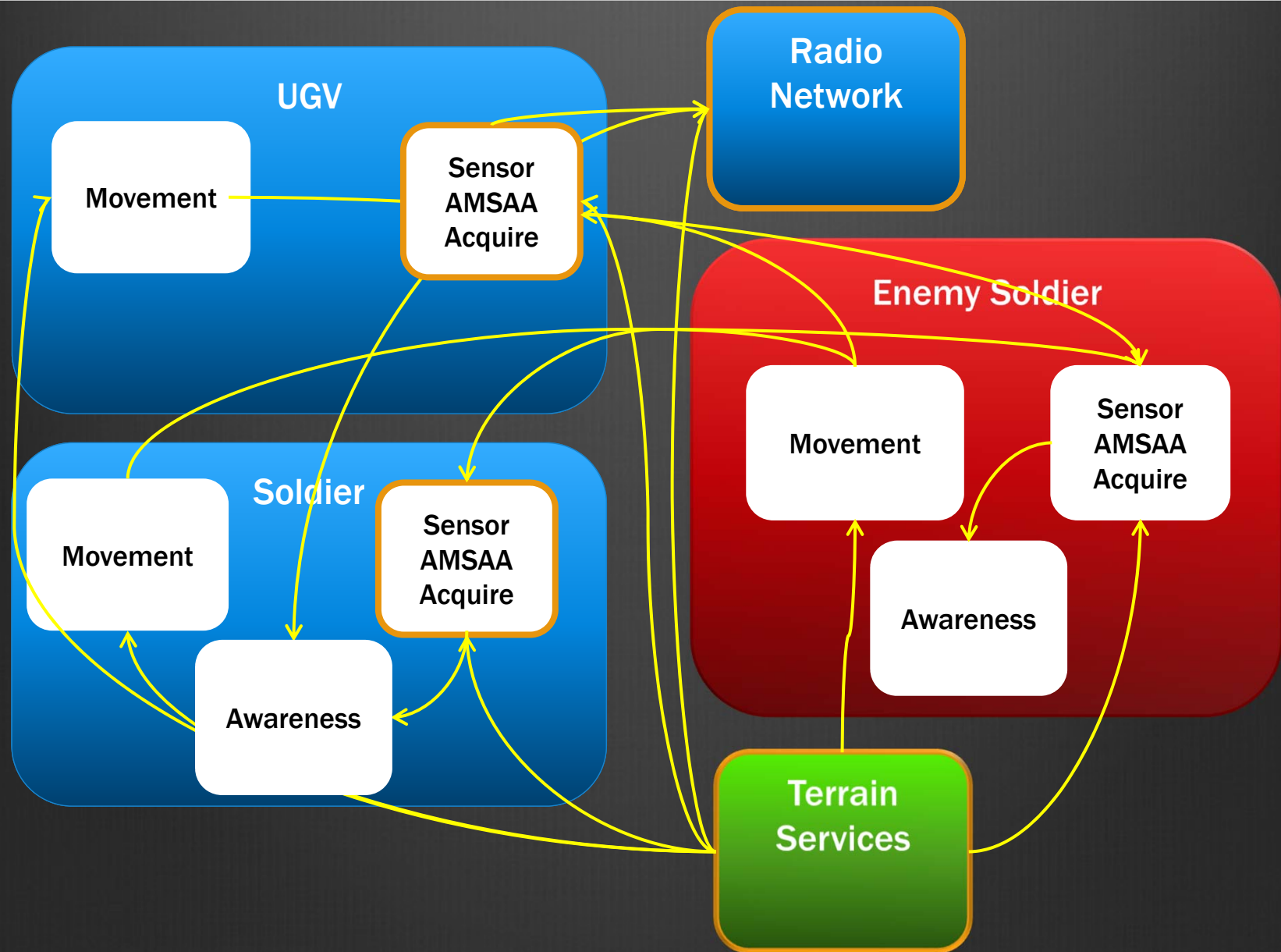


- ⊗ As DEVSActor
  - ⊗ Akka or C++ Actor Framework (CAF)
  - ⊗ Pass in initialization data at instantiation
  - ⊗ Define message interface
- ⊗ As a distributed actor
  - ⊗ Map message classes to messaging protocol such as:
    - ⊗ JSON
    - ⊗ Protocol Buffers
    - ⊗ XML
  - ⊗ Akka or CAF remote actors
  - ⊗ Document everything thoroughly
- ⊗ As simulation
  - ⊗ Compile tightly linked models in a coupled actor
  - ⊗ Compile models with heavy interaction traffic in same JVM (Akka) or native library (CAF)
  - ⊗ Control with execution engine
  - ⊗ Copy large interactive data sets such as terrain to each process to save network traffic





# Reference Implementation



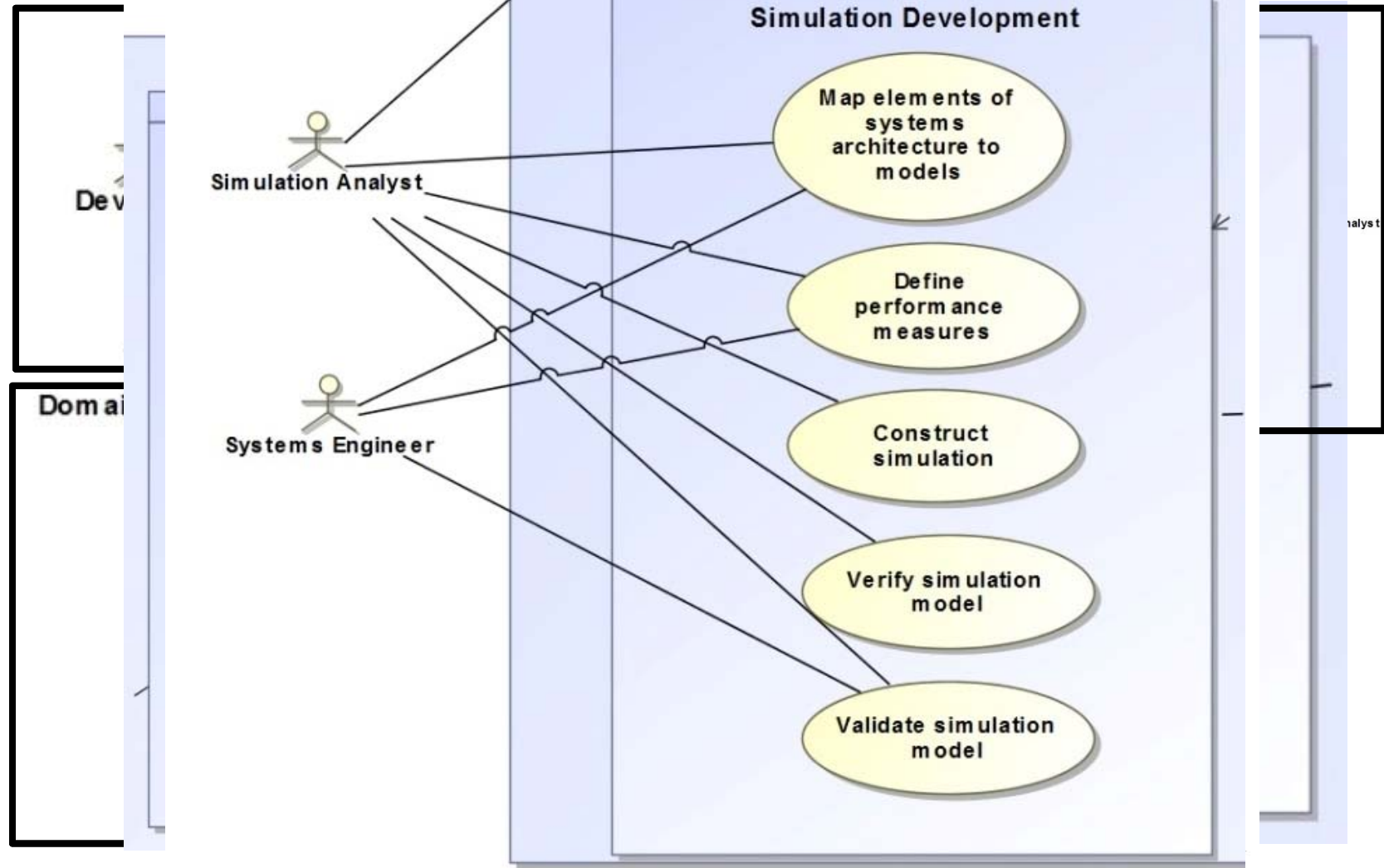
# Simulation Execution



# EASE-DMF Use Cases



uc [Package] UseCases [ DRS Use Cases





# Small Unmanned Aircraft Modeling Framework



PM UAS  
USMA  
AMRDEC

ARL STTC  
AMSAA  
NSRDEC

## Summary

- New SUAS acquisition strategy requires PM UAS to operate as lead systems integrator (LSI)
- LSI role requires assessment of engineering trades
- Develop a web-based integrated modeling and simulation framework to assess engineering trades for small unmanned aircraft systems

## Technical Approach

- Develop a series of discrete analysis models to represent small UAS technical performance
  - Target acquisition
  - Communications propagation
  - Situation awareness
  - Power
  - Flight dynamics
  - Terrain
- Wrap in web-based interface
- Integrate in simulation framework using Discrete Event Systems Specification (DEVS) and SysML

## Deliverables

- SysML architecture of proposed micro UAS
- Scenario development and design of experiments
- Simulation analysis of micro key UAS performance parameters tradespace
  - Size, weight, and power
  - Fixed vs. Rotary wing
  - Noise
  - Sensor performance
  - Radio performance
- Squad or platoon level mission performance metrics

# Functions of a DEVSActor

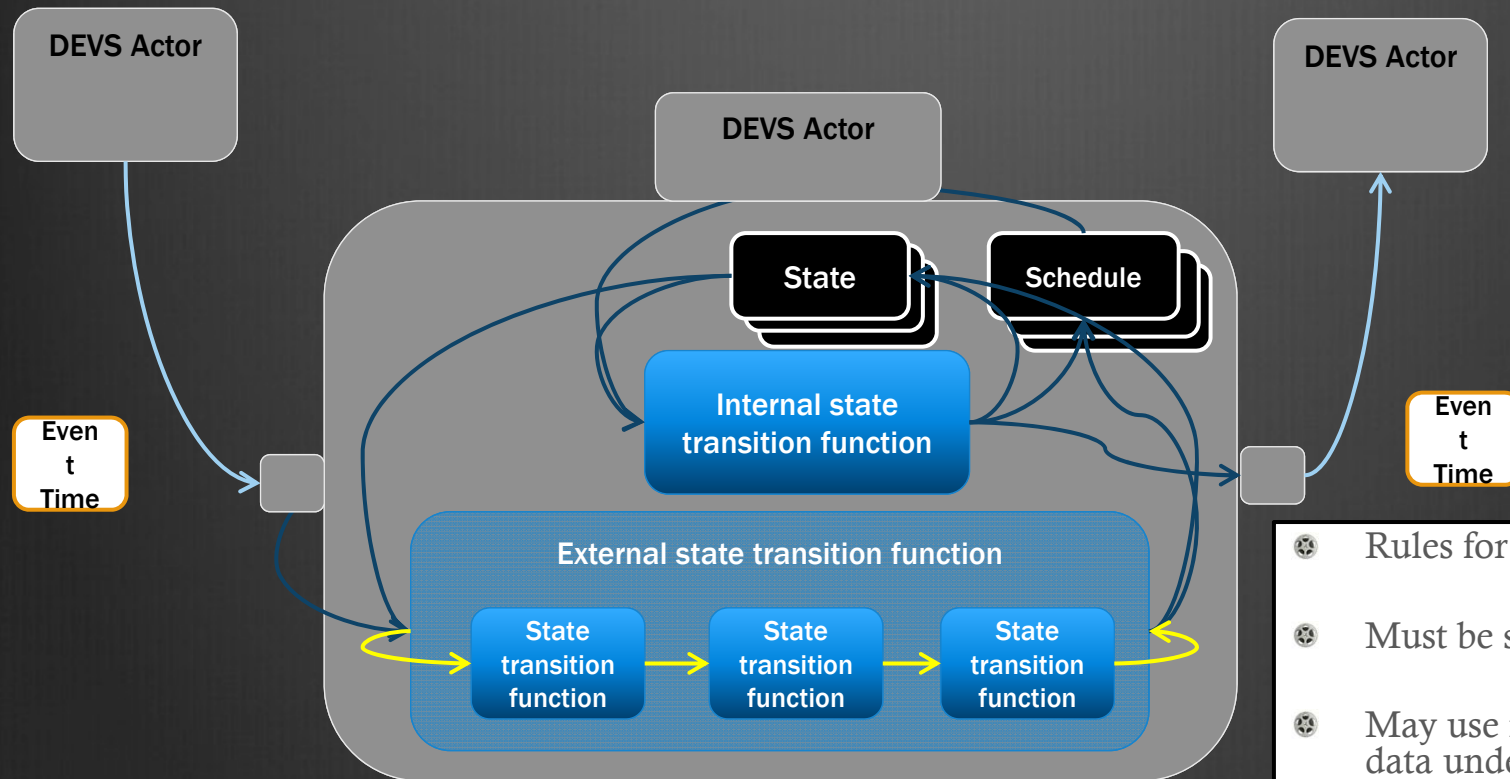


- ⦿ Initialize with static properties
- ⦿ Local and global virtual time
- ⦿ An internal schedule of state transitions
- ⦿ A set of internal and external state transition functions
- ⦿ It may update its state, schedule and internal event, or generate a message to other DEVSActors
- ⦿ Maintain record of internal state and drop as global time advances
- ⦿ List of events that may be replayed in the event of roll back
- ⦿ An ability to generate random variates needed by state transitions
- ⦿ A publish and subscribe mechanism that asks for a notification message upon sepecific state transitions of other DEVSActors



# M&S Composition

## State Transition Functions



- Functions are mathematically composable
- State transitions that take place at same instant can be chained into one state transition
- Calls out to stateless utility functions such as coordinate transformation

- Rules for functions:
- Must be stateless
- May use initialization data under closure
- These are static objects with only static data and methods
- After initialization, calling with same data always gives same answer